

ABSTRACT

A lever for grasping bone tissue includes a shaft defining a channel and having a proximal end and a distal end, a claw member disposed on the distal end of the shaft for holding the bone tissue, and a rod threadably received in the channel and having a proximal end and a distal end. Rotation of the rod with respect to the shaft causes the rod to move substantially axially with respect to the shaft to selectively position the distal end of the rod with respect to the claw member. The lever may further include a locking member to allow the rod to slide axially with respect to the shaft. Various other features which improve the functioning of the lever may be provided separately or in combination.

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